

# ALevel CS C23 Algorithm (1)

**Binary search:** repeated checking of the middle item in an ordered search list and discarding the half of the list which does not contain the search item

```

Found ← FALSE
SearchFailed ← FALSE
First ← 0
Last ← MaxItems – 1 // set boundaries of search area
WHILE NOT Found AND NOT SearchFailed DO
    Middle ← (First + Last) DIV 2 // find middle of current search
area
    IF List[Middle] = SearchItem
        THEN
            Found ← TRUE
        ELSE
            IF First >= Last // no search area left
                THEN
                    SearchFailed ← TRUE
                ELSE
                    IF List[Middle] > SearchItem
                        THEN // must be in first half
                            Last ← Middle - 1 // move upper boundary
                        ELSE // must be in second half
                            First ← Middle + 1 // move lower boundary
                    ENDIF
                ENDIF
            ENDIF
        ENDIF
    ENDWHILE
    IF Found = TRUE
        THEN
            OUTPUT Middle // output position where item was found
        ELSE
            OUTPUT "Item not present in array"
        ENDIF
    
```

## Create Linked List:

```

// NullPointer should be set to -1 if using array element with index 0
CONSTANT NullPointer = -1
// Declare record type to store data and pointer
TYPE ListNode
    DECLARE Data : STRING
    DECLARE Pointer : INTEGER
ENDTYPE Su
DECLARE StartPointer : INTEGER
DECLARE FreeListPtr : INTEGER
DECLARE List : ARRAY[0 : 6] OF ListNode

PROCEDURE InitialiseList
    StartPointer ← NullPointer // set start pointer
    FreeListPtr ← 0 // set starting position of free list
    FOR Index ← 0 TO 5 // link all nodes to make free list
        List[Index].Pointer ← Index + 1
    NEXT Index
    List[6].Pointer ← NullPointer // last node of free list
ENDPROCEDURE
    
```

## Delete a node from an ordered linked list

```

PROCEDURE DeleteNode(DataItem)
    ThisNodePtr ← StartPointer // start at beginning of list
    WHILE ThisNodePtr <> NullPointer // while not end of list
        AND List[ThisNodePtr].Data <> DataItem DO // and item not found
            PreviousNodePtr ← ThisNodePtr // remember this node
            // follow the pointer to the next node
            ThisNodePtr ← List[ThisNodePtr].Pointer
    ENDWHILE
    IF ThisNodePtr <> NullPointer // node exists in list
        THEN
            IF ThisNodePtr = StartPointer // first node to be deleted
                THEN
                    // move start pointer to the next node in list
                    StartPointer ← List[StartPointer].Pointer
                ELSE
                    // it is not the start node;
                    // so make the previous node's pointer point to
                    // the current node's 'next' pointer; thereby removing all
                    // references to the current pointer from the list
                    List[PreviousNodePtr].Pointer ← List[ThisNodePtr].Pointer
            ENDIF
            List[ThisNodePtr].Pointer ← FreeListPtr
            FreeListPtr ← ThisNodePtr
        ENDIF
    ENDPROCEDURE
    
```

## Linear search:

```

MaxIndex ← 6
INPUT SearchValue
Found ← FALSE
Index ← -1
REPEAT
    Index ← Index + 1
    IF myList[Index] = SearchValue
        THEN
            Found ← TRUE
    ENDIF
UNTIL FOUND = TRUE OR Index >= MaxIndex
IF Found = TRUE
    THEN
        OUTPUT "Value found at location: " Index
    ELSE
        OUTPUT "Value not found"
ENDIF
    
```

## Bubble sort:

```

n ← MaxIndex – 1
FOR i ← 0 TO MaxIndex – 1
    FOR j ← 0 TO n
        IF myList[j] > myList[j + 1]
            THEN
                Temp ← myList[j]
                myList[j] ← myList[j + 1]
                myList[j + 1] ← Temp
        ENDIF
    NEXT j
    n ← n – 1 // this means the next time
    round the inner loop, we don't
    // look at the values already in
    the correct positions.
NEXT i
    
```

## Insertion sort:

```

FOR Pointer ← 1 TO NumberOfitems – 1
    ItemToBeInserted ← List[Pointer]
    CurrentItem ← Pointer – 1 // pointer to last item in sorted part of list
    WHILE (List[CurrentItem] > ItemToBeInserted) AND (CurrentItem > -1) DO
        List[CurrentItem + 1] ← List[CurrentItem] // move current item down
        CurrentItem ← CurrentItem – 1 // look at the item above
    ENDWHILE
    List[CurrentItem + 1] ← ItemToBeInserted // insert item
NEXT Pointer
    
```

## Insert a node into an ordered list:

```

PROCEDURE InsertNode(NewItem)
    IF FreeListPtr <> NullPointer
        THEN // there is space in the array
            // take node from free list and store data item
            NewNodePtr ← FreeListPtr
            List[NewNodePtr].Data ← newItem
            FreeListPtr ← List[FreeListPtr].Pointer
            // find insertion point
            ThisNodePtr ← StartPointer // start at beginning of list
            PreviousNodePtr ← NullPointer
            WHILE ThisNodePtr <> NullPointer // while not end of list
                AND List[ThisNodePtr].Data < newItem DO
                    PreviousNodePtr ← ThisNodePtr // remember this node
                    // follow the pointer to the next node
                    ThisNodePtr ← List[ThisNodePtr].Pointer
            ENDWHILE
            IF PreviousNodePtr = StartPointer
                THEN // insert new node at start of list
                    List[NewNodePtr].Pointer ← StartPointer
                    StartPointer ← NewNodePtr
                ELSE // insert new node between previous node and this node
                    List[NewNodePtr].Pointer ← List[PreviousNodePtr].Pointer
                    List[PreviousNodePtr].Pointer ← NewNodePtr
            ENDIF
    ENDIF
ENDPROCEDURE
    
```

## Find an element in an ordered linked list

```

FUNCTION FindNode(DataItem) RETURNS INTEGER // returns pointer to node
    CurrentNodePtr ← StartPointer // start at beginning of list
    WHILE CurrentNodePtr <> NullPointer // not end of list
        AND List[CurrentNodePtr].Data <> DataItem DO // item not found
            // follow the pointer to the next node
            CurrentNodePtr ← List[CurrentNodePtr].Pointer
    ENDWHILE
    RETURN CurrentNodePtr // returns NullPointer if item not found
ENDFUNCTION
    
```

## Access all nodes stored in the linked list

```

PROCEDURE OutputAllNodes
    CurrentNodePtr ← StartPointer // start at beginning of list
    WHILE CurrentNodePtr <> NullPointer DO // while not end of list
        OUTPUT List[CurrentNodePtr].Data
        // follow the pointer to the next node
        CurrentNodePtr ← List[CurrentNodePtr].Pointer
    ENDWHILE
ENDPROCEDURE
    
```

# ALevel CS C23 Algorithm (2)

## Create a new binary tree

```
// NullPointer should be set to -1 if using array element with index 0
CONSTANT NullPointer = -1
// Declare record type to store data and pointers
TYPE TreeNode
    DECLARE Data : STRING
    DECLARE LeftPointer : INTEGER
    DECLARE RightPointer : INTEGER
ENDTYPE
DECLARE RootPointer : INTEGER
DECLARE FreePtr : INTEGER
DECLARE Tree : ARRAY[0 : 6] OF TreeNode
PROCEDURE InitialiseTree
    RootPointer ← NullPointer // set start pointer
    FreePtr ← 0 // set starting position of free list
    FOR Index ← 0 TO 5 // link all nodes to make free list
        Tree[Index].LeftPointer ← Index + 1
    NEXT Index
    Tree[6].LeftPointer ← NullPointer // last node of free list
ENDPROCEDURE
```

## Find a node in a binary tree

```
FUNCTION FindNode(SearchItem) RETURNS INTEGER // returns pointer to node
    ThisNodePtr ← RootPointer // start at the root of the tree
    WHILE ThisNodePtr <> NullPointer // while a pointer to follow
        AND Tree[ThisNodePtr].Data <> SearchItem DO // and search item not found
            IF Tree[ThisNodePtr].Data > SearchItem
                THEN // follow left pointer
                    ThisNodePtr ← Tree[ThisNodePtr].LeftPointer
            ELSE // follow right pointer
                ThisNodePtr ← Tree[ThisNodePtr].RightPointer
            ENDIF
        ENDWHILE
        RETURN ThisNodePtr // will return null pointer if search item not found
ENDFUNCTION
```

## Create a new queue

```
// NullPointer should be set to -1 if using array
element with index 0
CONSTANT EMPTYSTRING = ""
CONSTANT NullPointer = -1
CONSTANT MaxQueueSize = 8
DECLARE FrontOfQueuePointer : INTEGER
DECLARE EndOfQueuePointer : INTEGER
DECLARE NumberInQueue : INTEGER
DECLARE Queue : ARRAY[0 : MaxQueueSize - 1]
OF STRING
PROCEDURE InitialiseQueue
    FrontOfQueuePointer ← NullPointer // set front of
queue pointer
    EndOfQueuePointer ← NullPointer // set end of
queue pointer
    NumberInQueue ← 0 // no elements in queue
ENDPROCEDURE
```

## Create a new stack

```
// NullPointer should be set to -1 if using array
element with index 0
CONSTANT EMPTYSTRING = ""
CONSTANT NullPointer = -1
CONSTANT MaxStackSize = 8
DECLARE BaseOfStackPointer : INTEGER
DECLARE TopOfStackPointer : INTEGER
DECLARE Stack : ARRAY[1 : MaxStackSize - 1]
OF STRING
PROCEDURE InitialiseStack
    BaseOfStackPointer ← 0 // set base of stack
pointer
    TopOfStackPointer ← NullPointer // set top of
stack pointer
ENDPROCEDURE
```

## Hash table

hashing: Calculating an address from a key is called '**hashing**'.

If two different key values hash to the same address this is called a '**collision**'.

### There are different ways to handle collisions:

1. chaining: create a linked list for collisions with start pointer at the hashed address
2. using overflow areas: all collisions are stored in a separate overflow area, known as 'closed hashing'
3. using neighbouring slots: perform a linear search from the hashed address to find an empty slot, known as 'open hashing'.

## Insert a new node into a binary tree

```
PROCEDURE InsertNode(NewItem)
    IF FreePtr <> NullPointer
        THEN // there is space in the array
            // take node from free list, store data item, set null pointers
            NewNodePtr ← FreePtr
            FreePtr ← Tree[FreePtr].LeftPointer
            Tree[NewNodePtr].Data ← NewItem
            Tree[NewNodePtr].LeftPointer ← NullPointer
            Tree[NewNodePtr].RightPointer ← NullPointer
            // check if empty tree
            IF RootPointer = NullPointer
                THEN // insert new node at root
                    RootPointer ← NewNodePtr
            ELSE // find insertion point
                ThisNodePtr ← RootPointer // start at the root of the tree
                WHILE ThisNodePtr <> NullPointer DO // while not a leaf node
                    PreviousNodePtr ← ThisNodePtr // remember this node
                    IF Tree[ThisNodePtr].Data > NewItem
                        THEN // follow left pointer
                            TurnedLeft ← TRUE
                            ThisNodePtr ← Tree[ThisNodePtr].LeftPointer
                    ELSE // follow right pointer
                            TurnedLeft ← FALSE
                            ThisNodePtr ← Tree[ThisNodePtr].RightPointer
                    ENDIF
                ENDWHILE
                IF TurnedLeft = TRUE
                    THEN
                        Tree[PreviousNodePtr].LeftPointer ← NewNodePtr
                    ELSE
                        Tree[PreviousNodePtr].RightPointer ← NewNodePtr
                    ENDIF
                ENDIF
            ENDPROCEDURE
```

## Add an item to the queue

```
PROCEDURE AddToQueue(NewItem)
    IF NumberInQueue < MaxQueueSize
        THEN // there is space in the queue
            // increment end of queue pointer
            EndOfQueuePointer ←
EndOfQueuePointer + 1
            // check for wrap-round
            IF EndOfQueuePointer > MaxQueueSize -
1
                THEN // wrap to beginning of array
                    EndOfQueuePointer ← 0 // add item to
end of queue
                ENDIF
                Queue[EndOfQueuePointer] ← NewItem
                // increment counter
                NumberInQueue ← NumberInQueue + 1
            ENDIF
    ENDPROCEDURE
```

## Pop an item off the stack

```
FUNCTION Pop()
    DECLARE Item : STRING
    Item ← EMPTYSTRING
    IF TopOfStackPointer > NullPointer
        THEN // there is at least one item on the
stack
            // pop item off the top of the stack
            Item ← Stack[TopOfStackPointer]
            // decrement top of stack pointer
            TopOfStackPointer ← TopOfStackPointer -
1
        ENDIF
    RETURN Item
ENDFUNCTION
```

## Insert a record into a hash table

```
PROCEDURE Insert(NewRecord)
    Index ← Hash(NewRecord.Key)
    WHILE HashTable[Index] NOT empty DO
        Index ← Index + 1 // go to next slot to check if
empty
        IF Index > Max // beyond table boundary?
            THEN // wrap around to beginning of table
                Index ← 0
        ENDIF
    ENDWHILE
    HashTable[Index] ← NewRecord
ENDPROCEDURE
```

## Remove an item from the queue

```
FUNCTION RemoveFromQueue()
    DECLARE Item : STRING
    Item ← EMPTYSTRING
    IF NumberInQueue > 0
        THEN // there is at least one item in the queue
            // remove item from the front of the queue
            Item ← Queue[FrontOfQueuePointer]
            NumberInQueue ← NumberInQueue - 1
            IF NumberInQueue = 0
                THEN // if queue empty, reset pointers
                    CALL InitialiseQueue
            ELSE // increment front of queue pointer
                FrontOfQueuePointer ← FrontOfQueuePointer + 1
                // check for wrap-round
                IF FrontOfQueuePointer > MaxQueueSize - 1
                    THEN // wrap to beginning of array
                        FrontOfQueuePointer ← 0
                ENDIF
            ENDIF
        RETURN Item
    ENDFUNCTION
```

## Push an item onto the stack

```
PROCEDURE Push(NewItem)
    IF TopOfStackPointer < MaxStackSize - 1
        THEN // there is space on the stack
            // increment top of stack pointer
            TopOfStackPointer ← TopOfStackPointer + 1
            // add item to top of
            Stack[TopOfStackPointer] ← NewItem
        ENDIF
    ENDPROCEDURE
```

## Find a record in a hash table

```
FUNCTION FindRecord(SearchKey) RETURNS Record
    Index ← Hash(SearchKey)
    WHILE (HashTable[Index].Key <> SearchKey)
        AND (HashTable[Index] NOT empty) DO
            Index ← Index + 1 // go to next slot
            IF Index > Max // beyond table boundary?
                THEN // wrap around to beginning of table
                    Index ← 0
            ENDIF
    ENDWHILE
    IF HashTable[Index] NOT empty // if record found
        THEN
            RETURN HashTable[Index] // return the record
        ENDIF
    ENDFUNCTION
```

# ALevel CS C26 File processing and Exception

## Records

pseudocode:

```
TYPE CarRecord
    DECLARE VehicleID : STRING
    DECLARE Registration : STRING
    DECLARE DateOfRegistration : DATE
    DECLARE EngineSize : INTEGER
    DECLARE PurchasePrice : CURRENCY
ENDTYPE
```

```
// declare a variable
DECLARE ThisCar : CarRecord
python:
class CarRecord: # declaring a class without other methods
    def __init__(self): # constructor
        self.VehicleID = ""
        self.Registration = ""
        self.DateOfRegistration = None
        self.EngineSize = 0
        self.PurchasePrice = 0.00
ThisCar = CarRecord() # instantiates a car record
ThisCar.EngineSize = 2500 # assign a value to a field
Car = [CarRecord() for i in range(100)] # make a list of 100 car
records
Car[1].EngineSize = 2500 # assign value to a field of the 2nd car in
list
```

## Random-access file processing

pseudocode:

```
// Saving a record
OPENFILE CarFile FOR RANDOM
Address ← Hash(ThisCar.VehicleID)
SEEK CarFile, Address
PUTRECORD CarFile, ThisCar
CLOSEFILE CarFile

// Retrieving a record
OPENFILE CarFile FOR RANDOM
Address ← Hash(ThisCar.VehicleID)
SEEK CarFile, Address
GETRECORD CarFile, ThisCar
CLOSEFILE CarFile
```

python:

```
import pickle # this library is required to create binary files
ThisCar = CarRecord()
CarFile = open('CarFile.DAT','rb+') # open file for binary read and write
Address = hash(ThisCar.VehicleID)
CarFile.seek(Address)
pickle.dump(ThisCar, CarFile) # write a whole record to the binary file
CarFile.close() # close file
# to find a record from a given VehicleID:
CarFile = open('CarFile.DAT','rb') # open file for binary read
Address = hash(VehicleID)
CarFile.seek(Address)
ThisCar = pickle.load(CarFile) # load record from file
CarFile.close()
```

## Exception

```
python:
NumberString = input("Enter an integer: ")
try:
    n = int(NumberString)
    print(n)
except:
    print("This was not an integer")
```

## Sequential file processing

pseudocode:

```
// Saving content of array
OPENFILE CarFile FOR WRITE
FOR i ← 1 TO MaxRecords
    PUTRECORD CarFile, Car[i]
NEXT i
CLOSEFILE CarFile

// Restoring contents of array
OPENFILE CarFile FOR READ
FOR i ← 1 TO MaxRecords
    GETRECORD CarFile, Car[i]
NEXT i
CLOSEFILE CarFile
```

python:

```
import pickle # this library is required to create binary files
Car = [CarRecord() for i in range(100)]

CarFile = open('CarFile.DAT', 'wb') # open file for binary write

for i in range(100): # loop for each array element
    pickle.dump(Car[i], CarFile) # write a whole record to the binary file

CarFile.close() # close file

CarFile = open('CarFile.DAT', 'rb') # open file for binary read

Car = [] # start with empty list
while True: # check for end of file
    Car.append(pickle.load(CarFile)) # append record from file to end of list

CarFile.close()
```