

A Level CS C23 Algorithm (1)

Binary search: repeated checking of the middle item in an ordered search list and discarding the half of the list which does not contain the search item

```
Found ← FALSE
SearchFailed ← FALSE
First ← 0
Last ← MaxItems – 1 // set boundaries of search area
WHILE NOT Found AND NOT SearchFailed DO
    Middle ← (First + Last) DIV 2 // find middle of current search area
    IF List[Middle] = SearchItem
        THEN
            Found ← TRUE
    ELSE
        IF First >= Last // no search area left
            THEN
                SearchFailed ← TRUE
        ELSE
            IF List[Middle] > SearchItem
                THEN // must be in first half
                    Last ← Middle - 1 // move upper boundary
            ELSE // must be in second half
                First ← Middle + 1 // move lower boundary
        ENDIF
    ENDIF
ENDIF
ENDIF
ENDWHILE
IF Found = TRUE
    THEN
        OUTPUT Middle // output position where item was found
    ELSE
        OUTPUT "Item not present in array"
    ENDIF
ENDIF
```

Linear search:

```
MaxIndex ← 6
INPUT SearchValue
Found ← FALSE
Index ← -1
REPEAT
    Index ← Index + 1
    IF MyList[Index] = SearchValue
        THEN
            Found ← TRUE
    ENDIF
UNTIL FOUND = TRUE OR Index >= MaxIndex
IF Found = TRUE
    THEN
        OUTPUT "Value found at location: " Index
    ELSE
        OUTPUT "Value not found"
    ENDIF
ENDIF
```

Bubble sort:

```
n ← MaxIndex – 1
FOR i ← 0 TO MaxIndex – 1
    FOR j ← 0 TO n
        IF MyList[j] > MyList[j + 1]
            THEN
                Temp ← MyList[j]
                MyList[j] ← MyList[j + 1]
                MyList[j + 1] ← Temp
        ENDIF
    NEXT j
    n ← n – 1 // this means the next time
    // look at the values already in
    // the correct positions.
NEXT i
```

Insertion sort:

```
FOR Pointer ← 1 TO NumberOfItems – 1
    ItemToBeInserted ← List[Pointer]
    CurrentItem ← Pointer – 1 // pointer to last item in sorted part of list
    WHILE (List[CurrentItem] > ItemToBeInserted) AND (CurrentItem > -1) DO
        List[CurrentItem + 1] ← List[CurrentItem] // move current item down
        CurrentItem ← CurrentItem – 1 // look at the item above
    ENDWHILE
    List[CurrentItem + 1] ← ItemToBeInserted // insert item
NEXT Pointer
```

Create Linked List:

```
// NullPointer should be set to -1 if using array element with index 0
CONSTANT NullPointer = -1
// Declare record type to store data and pointer
TYPE ListNode
    DECLARE Data : STRING
    DECLARE Pointer : INTEGER
ENDTYPE Su
DECLARE StartPointer : INTEGER
DECLARE FreeListPtr : INTEGER
DECLARE List : ARRAY[0 : 6] OF ListNode

PROCEDURE InitialiseList
    StartPointer ← NullPointer // set start pointer
    FreeListPtr ← 0 // set starting position of free list
    FOR Index ← 0 TO 5 // link all nodes to make free list
        List[Index].Pointer ← Index + 1
    NEXT Index
    List[6].Pointer ← NullPointer // last node of free list
ENDPROCEDURE
```

Delete a node from an ordered linked list

```
PROCEDURE DeleteNode(DataItem)
    ThisNodePtr ← StartPointer // start at beginning of list
    WHILE ThisNodePtr <> NullPointer // while not end of list
        AND List[ThisNodePtr].Data <> DataItem DO // and item not found
            PreviousNodePtr ← ThisNodePtr // remember this node
            // follow the pointer to the next node
            ThisNodePtr ← List[ThisNodePtr].Pointer
        ENDWHILE
    IF ThisNodePtr <> NullPointer // node exists in list
        THEN
            IF ThisNodePtr = StartPointer // first node to be deleted
                THEN
                    // move start pointer to the next node in list
                    StartPointer ← List[StartPointer].Pointer
            ELSE
                // it is not the start node;
                // so make the previous node's pointer point to
                // the current node's 'next' pointer; thereby removing all
                // references to the current pointer from the list
                List[PreviousNodePtr].Pointer ← List[ThisNodePtr].Pointer
            ENDIF
            List[ThisNodePtr].Pointer ← FreeListPtr
            FreeListPtr ← ThisNodePtr
        ENDIF
    ENDPROCEDURE
```

Insert a node into an ordered list:

```
PROCEDURE InsertNode(NewItem)
    IF FreeListPtr <> NullPointer
        THEN // there is space in the array
            // take node from free list and store data item
            NewNodePtr ← FreeListPtr
            List[NewNodePtr].Data ← NewItem
            FreeListPtr ← List[FreeListPtr].Pointer
            // find insertion point
            ThisNodePtr ← StartPointer // start at beginning of list
            PreviousNodePtr ← NullPointer
            WHILE ThisNodePtr <> NullPointer // while not end of list
                AND List[ThisNodePtr].Data < NewItem DO
                    PreviousNodePtr ← ThisNodePtr // remember this node
                    // follow the pointer to the next node
                    ThisNodePtr ← List[ThisNodePtr].Pointer
            ENDWHILE
            IF PreviousNodePtr = StartPointer
                THEN // insert new node at start of list
                    List[NewNodePtr].Pointer ← StartPointer
                    StartPointer ← NewNodePtr
            ELSE // insert new node between previous node and this node
                List[NewNodePtr].Pointer ← List[PreviousNodePtr].Pointer
                List[PreviousNodePtr].Pointer ← NewNodePtr
            ENDIF
        ENDIF
    ENDPROCEDURE
```

Find an element in an ordered linked list

```
FUNCTION FindNode(DataItem) RETURNS INTEGER // returns pointer to node
    CurrentNodePtr ← StartPointer // start at beginning of list
    WHILE CurrentNodePtr <> NullPointer // not end of list
        AND List[CurrentNodePtr].Data <> DataItem DO // item not found
            // follow the pointer to the next node
            CurrentNodePtr ← List[CurrentNodePtr].Pointer
        ENDWHILE
    RETURN CurrentNodePtr // returns NullPointer if item not found
ENDFUNCTION
```

Access all nodes stored in the linked list

```
PROCEDURE OutputAllNodes
    CurrentNodePtr ← StartPointer // start at beginning of list
    WHILE CurrentNodePtr <> NullPointer DO // while not end of list
        OUTPUT List[CurrentNodePtr].Data
        // follow the pointer to the next node
        CurrentNodePtr ← List[CurrentNodePtr].Pointer
    ENDWHILE
ENDPROCEDURE
```

ALevel CS C23 Algorithm (2)

Create a new binary tree <pre>// NullPointer should be set to -1 if using array element with index 0 CONSTANT NullPointer = -1 // Declare record type to store data and pointers TYPE TreeNode DECLARE Data : STRING DECLARE LeftPointer : INTEGER DECLARE RightPointer : INTEGER ENDTYPE DECLARE RootPointer : INTEGER DECLARE FreePtr : INTEGER DECLARE Tree : ARRAY[0 : 6] OF TreeNode PROCEDURE InitialiseTree RootPointer ← NullPointer // set start pointer FreePtr ← 0 // set starting position of free list FOR Index ← 0 TO 5 // link all nodes to make free list Tree[Index].LeftPointer ← Index + 1 NEXT Index Tree[6].LeftPointer ← NullPointer // last node of free list ENDPROCEDURE</pre>	Insert a new node into a binary tree <pre>PROCEDURE InsertNode(NewItem) IF FreePtr <> NullPointer THEN // there is space in the array // take node from free list, store data item, set null pointers NewNodePtr ← FreePtr FreePtr ← Tree[FreePtr].LeftPointer Tree[NewNodePtr].Data ← NewItem Tree[NewNodePtr].LeftPointer ← NullPointer Tree[NewNodePtr].RightPointer ← NullPointer // check if empty tree IF RootPointer = NullPointer THEN // insert new node at root RootPointer ← NewNodePtr ELSE // find insertion point ThisNodePtr ← RootPointer // start at the root of the tree WHILE ThisNodePtr <> NullPointer DO // while not a leaf node PreviousNodePtr ← ThisNodePtr // remember this node IF Tree[ThisNodePtr].Data > NewItem THEN // follow left pointer TurnedLeft ← TRUE ThisNodePtr ← Tree[ThisNodePtr].LeftPointer ELSE // follow right pointer TurnedLeft ← FALSE ThisNodePtr ← Tree[ThisNodePtr].RightPointer ENDIF ENDWHILE IF TurnedLeft = TRUE THEN Tree[PreviousNodePtr].LeftPointer ← NewNodePtr ELSE Tree[PreviousNodePtr].RightPointer ← NewNodePtr ENDIF ENDIF ENDIF ENDIF ENDIF ENDPROCEDURE</pre>	
Find a node in a binary tree <pre>FUNCTION FindNode(SearchItem) RETURNS INTEGER // returns pointer to node ThisNodePtr ← RootPointer // start at the root of the tree WHILE ThisNodePtr <> NullPointer // while a pointer to follow AND Tree[ThisNodePtr].Data <> SearchItem DO // and search item not found IF Tree[ThisNodePtr].Data > SearchItem THEN // follow left pointer ThisNodePtr ← Tree[ThisNodePtr].LeftPointer ELSE // follow right pointer ThisNodePtr ← Tree[ThisNodePtr].RightPointer ENDIF ENDWHILE RETURN ThisNodePtr // will return null pointer if search item not found ENDFUNCTION</pre>		
Create a new queue <pre>// NullPointer should be set to -1 if using array element with index 0 CONSTANT EMPTYSTRING = "" CONSTANT NullPointer = -1 CONSTANT MaxQueueSize = 8 DECLARE FrontOfQueuePointer : INTEGER DECLARE EndOfQueuePointer : INTEGER DECLARE NumberInQueue : INTEGER DECLARE Queue : ARRAY[0 : MaxQueueSize - 1] OF STRING PROCEDURE InitialiseQueue FrontOfQueuePointer ← NullPointer // set front of queue pointer EndOfQueuePointer ← NullPointer // set end of queue pointer NumberInQueue ← 0 // no elements in queue ENDPROCEDURE</pre>	Add an item to the queue <pre>PROCEDURE AddToQueue(NewItem) IF NumberInQueue < MaxQueueSize THEN // there is space in the queue // increment end of queue pointer EndOfQueuePointer ← EndOfQueuePointer + 1 // check for wrap-round IF EndOfQueuePointer > MaxQueueSize - 1 THEN // wrap to beginning of array EndOfQueuePointer ← 0 // add item to end of queue ENDIF Queue[EndOfQueuePointer] ← NewItem // increment counter NumberInQueue ← NumberInQueue + 1 ENDIF ENDPROCEDURE</pre>	Remove an item from the queue <pre>FUNCTION RemoveFromQueue() DECLARE Item : STRING Item ← EMPTYSTRING IF NumberInQueue > 0 THEN // there is at least one item in the queue // remove item from the front of the queue Item ← Queue[FrontOfQueuePointer] NumberInQueue ← NumberInQueue - 1 IF NumberInQueue = 0 THEN // if queue empty, reset pointers CALL InitialiseQueue ELSE // increment front of queue pointer FrontOfQueuePointer ← FrontOfQueuePointer + 1 // check for wrap-round IF FrontOfQueuePointer > MaxQueueSize - 1 THEN // wrap to beginning of array FrontOfQueuePointer ← 0 ENDIF ENDIF ENDIF ENDIF ENDIF RETURN Item ENDFUNCTION</pre>
Create a new stack <pre>// NullPointer should be set to -1 if using array element with index 0 CONSTANT EMPTYSTRING = "" CONSTANT NullPointer = -1 CONSTANT MaxStackSize = 8 DECLARE BaseOfStackPointer : INTEGER DECLARE TopOfStackPointer : INTEGER DECLARE Stack : ARRAY[1 : MaxStackSize - 1] OF STRING PROCEDURE InitialiseStack BaseOfStackPointer ← 0 // set base of stack pointer TopOfStackPointer ← NullPointer // set top of stack pointer ENDPROCEDURE</pre>	Pop an item off the stack <pre>FUNCTION Pop() DECLARE Item : STRING Item ← EMPTYSTRING IF TopOfStackPointer > NullPointer THEN // there is at least one item on the stack // pop item off the top of the stack Item ← Stack[TopOfStackPointer] // decrement top of stack pointer TopOfStackPointer ← TopOfStackPointer - 1 ENDIF RETURN Item ENDFUNCTION</pre>	Push an item onto the stack <pre>PROCEDURE Push(NewItem) IF TopOfStackPointer < MaxStackSize - 1 THEN // there is space on the stack // increment top of stack pointer TopOfStackPointer ← TopOfStackPointer + 1 // add item to top of Stack[TopOfStackPointer] ← NewItem ENDIF ENDPROCEDURE</pre>
Hash table hashing: Calculating an address from a key is called 'hashing'. If two different key values hash to the same address this is called a 'collision'. There are different ways to handle collisions: - chaining: create a linked list for collisions with start pointer at the hashed address - using overflow areas: all collisions are stored in a separate overflow area, known as 'closed hashing' - using neighbouring slots: perform a linear search from the hashed address to find an empty slot, known as 'open hashing'.	Insert a record into a hash table <pre>PROCEDURE Insert(NewRecord) Index ← Hash(NewRecord.Key) WHILE HashTable[Index] NOT empty DO Index ← Index + 1 // go to next slot to check if empty IF Index > Max // beyond table boundary? THEN // wrap around to beginning of table Index ← 0 ENDIF ENDWHILE HashTable[Index] ← NewRecord ENDPROCEDURE</pre>	Find a record in a hash table <pre>FUNCTION FindRecord(SearchKey) RETURNS Record Index ← Hash(SearchKey) WHILE (HashTable[Index].Key <> SearchKey) AND (HashTable[Index] NOT empty) DO Index ← Index + 1 // go to next slot IF Index > Max // beyond table boundary? THEN // wrap around to beginning of table Index ← 0 ENDIF ENDWHILE IF HashTable[Index] NOT empty // if record found THEN RETURN HashTable[Index] // return the record ENDIF ENDFUNCTION</pre>

Add an item to the queue